



The Joint Research Project SIMULTAN

WP3.1: GNSS Campaigns and Research

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Urban GNSS Sites and Campaign Design

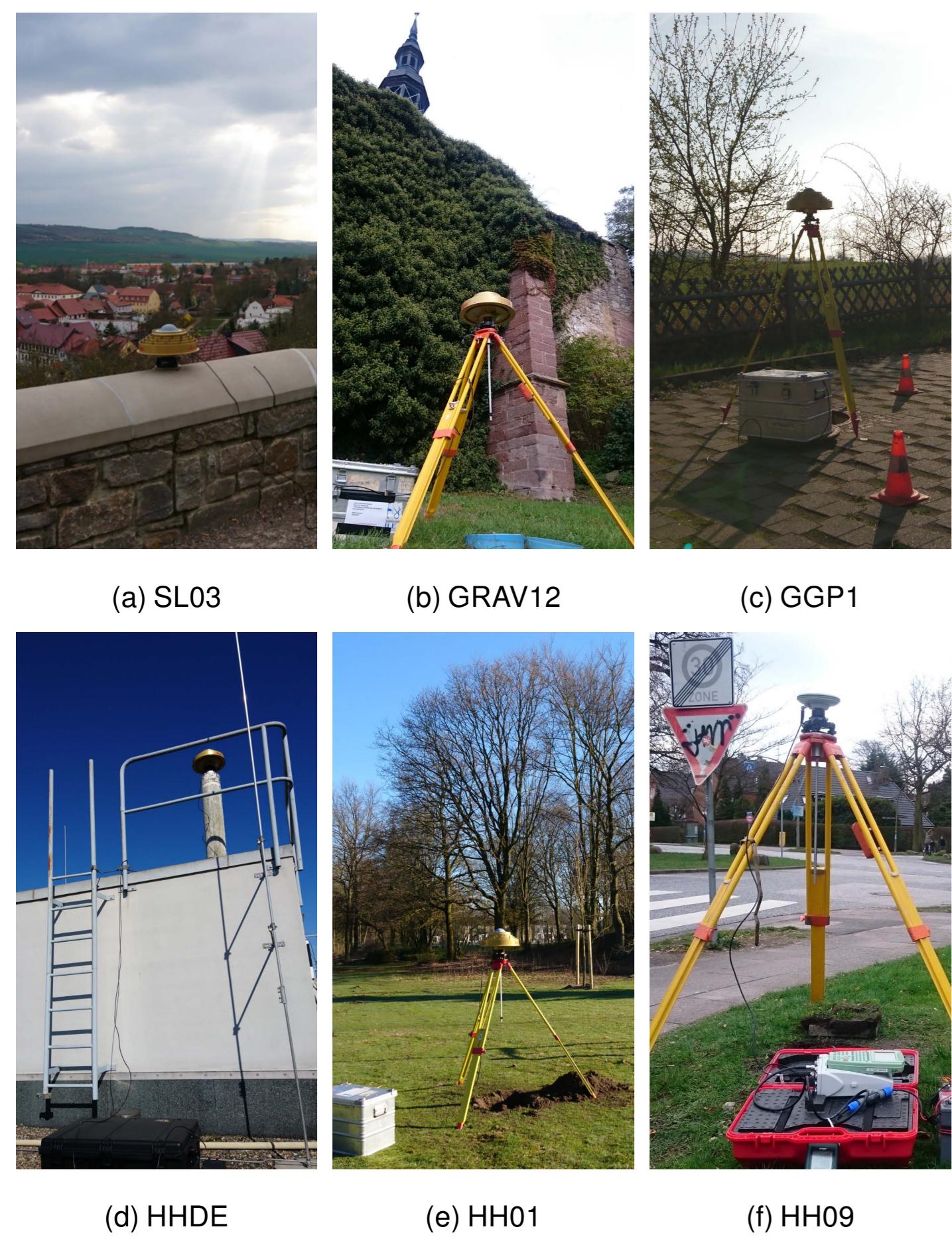


Figure 1: Co-located urban GNSS sites as part of geo-monitoring networks to control and observe subsidence processes, (a-c) Bad Frankenhausen (Thuringia), (d-f) Hamburg Groß-Flottbek.

SIMULTAN-Project

- Sinkhole Instability, MULTiscale monitoring and ANalysis: gain a deeper understanding of the complex processes, interactions and characteristics of the underground and the surface interaction in urban environments, [Kersten et al., 2017].

GNSS-Campaign Design in SIMULTAN

- Multi-GNSS equipment (Leica GRX1200+GNSS, Novatel 703GGG, Leica AR25.R3) with height adaptor FG ANA 100B for precise height determination.
- Four hour sessions, at least 3 independent repetitions per site.
- Data recording (1 Hz) at co-located sites (GNSS, levelling, gravimetry).
- Star-like GNSS monitoring network, fixed in local reference stations.

Urban GNSS Sites

- Urban infrastructure yields to variable and high multipath as well as challenging satellite geometry at each co-located site.
- Short baselines of approx. 700-1800 m.

Hamburg - Network

- **HHDE:** Local reference station at DESY (Deutsches Elektronen-Synchrotron), stability check by SAPOS® stations (Lower Saxony) Buchholz (0680), Stade2 (1662), Lüneburg (0660).
- **HH01:** Co-located site in a park with several trees which reduces satellite visibility at low elevations.
- **HH05:** Site located in proposed stable environment, northern part, close to DESY. Used to monitor subsidence in Wobbe-See (HH02-HH04) and the old storage basin (HH08).
- **HH03:** Co-located site to monitor subsidence; challenging satellite visibility, cf Fig. 3.

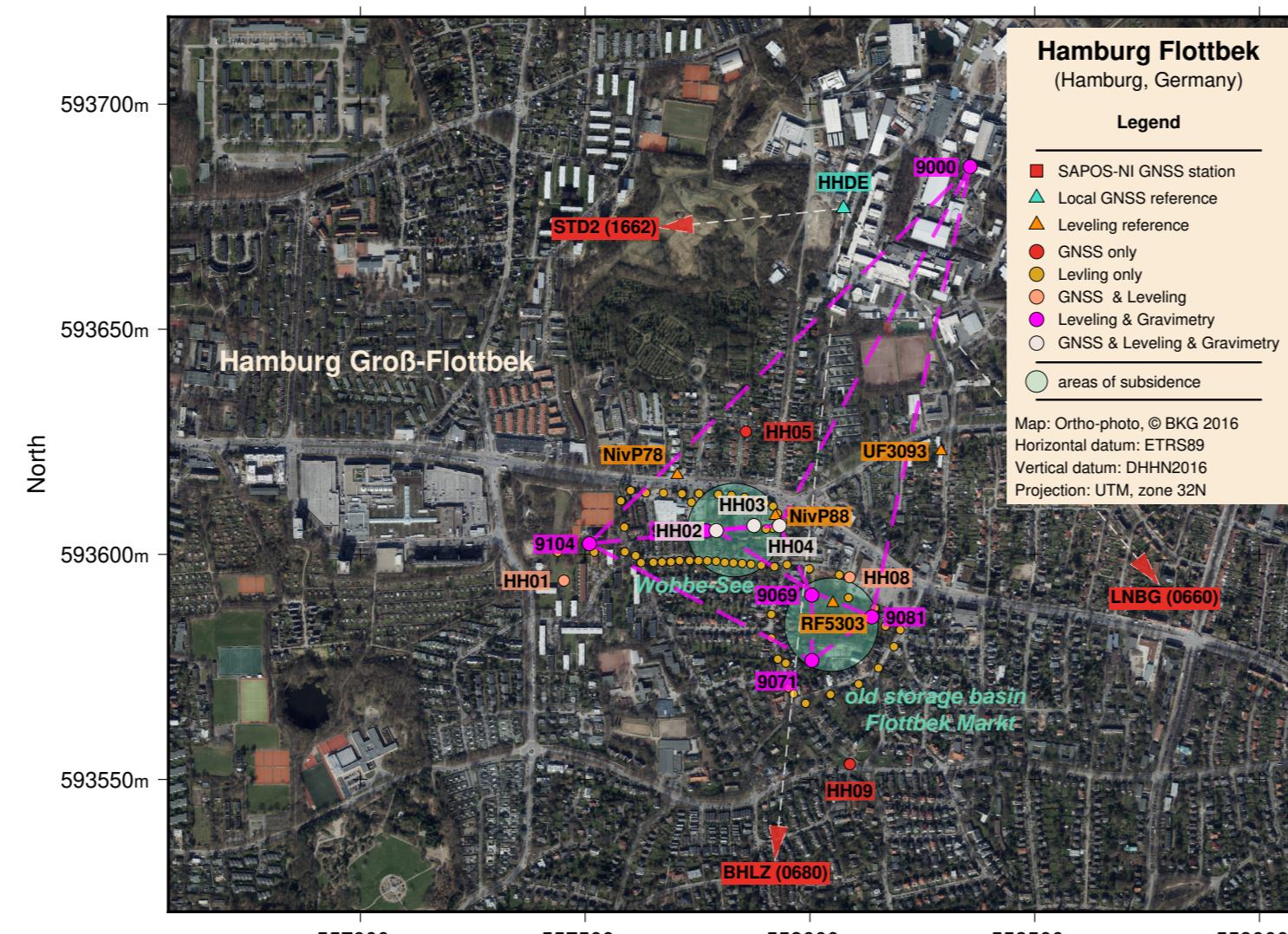
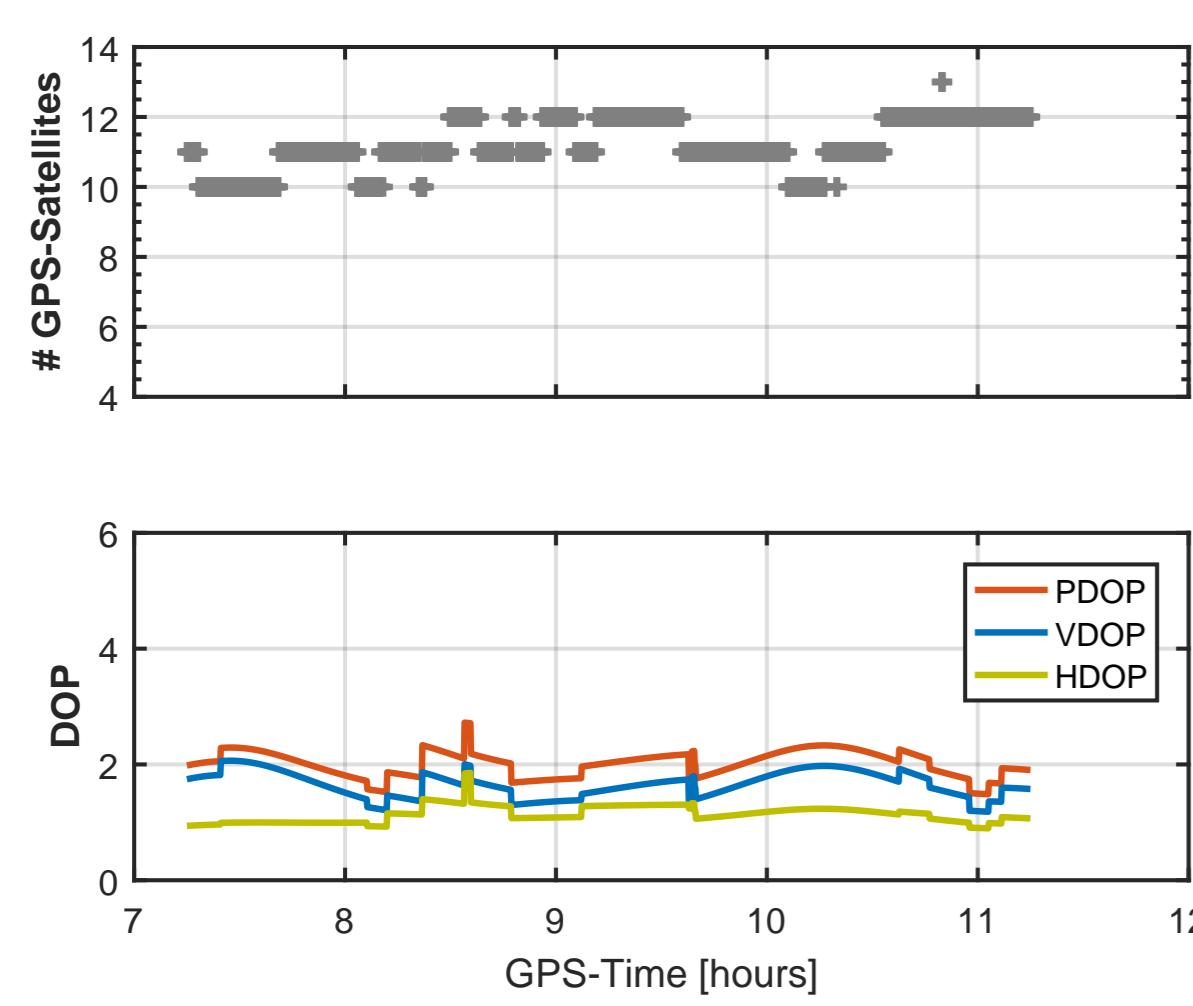
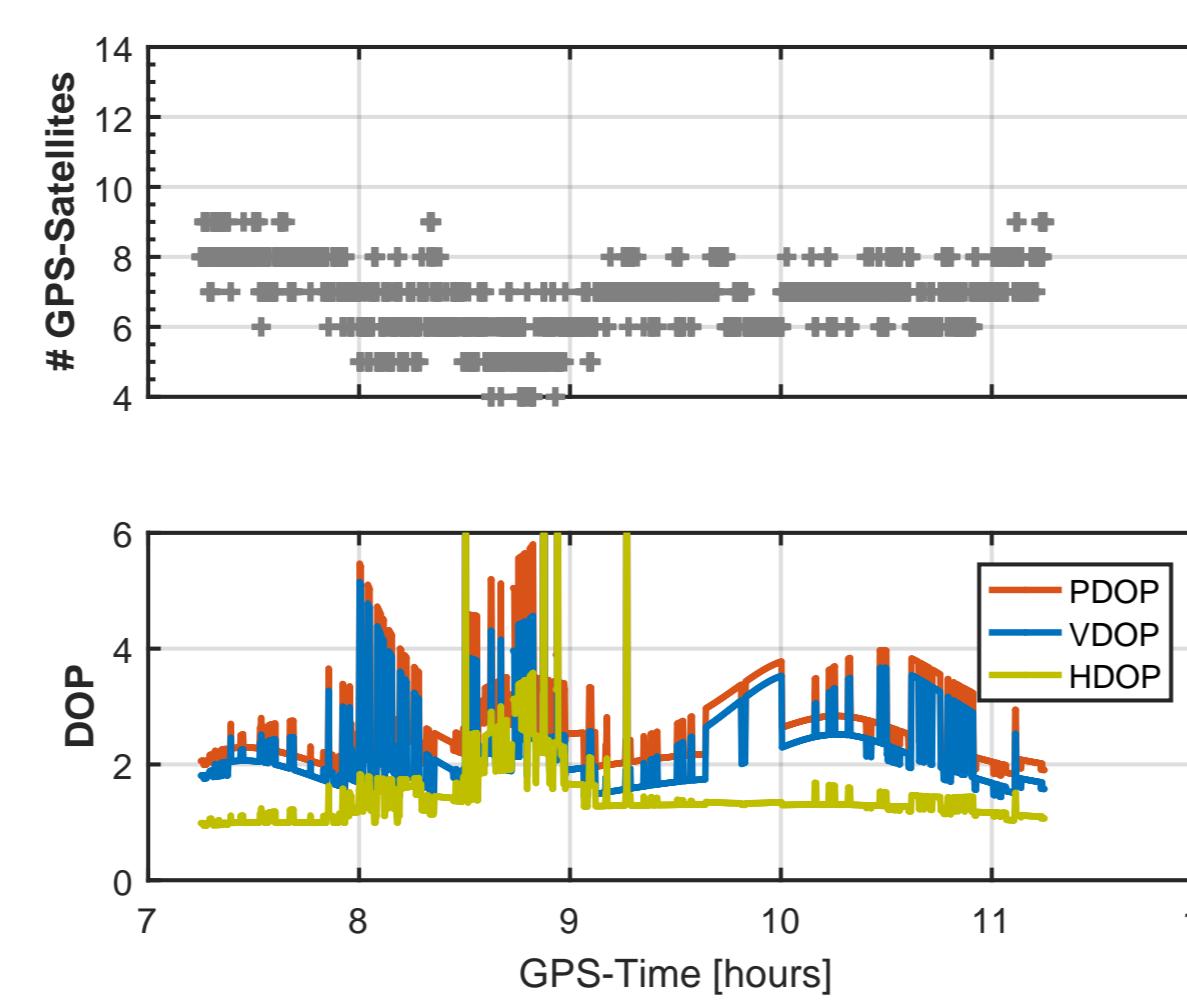


Figure 2: Combined geophysical network in Hamburg, Groß-Flottbek.



(a) DOP values at HHDE



(b) DOP values at HH03

Figure 3: Comparison of several DOP-Values (dilution of precision) and overall satellite visibility as quality indicators for characteristic sites of the monitoring network for the local Reference HHDE (a) and a site in the Wobbe-See subsidence area HH03 (b).

Hamburg - Details

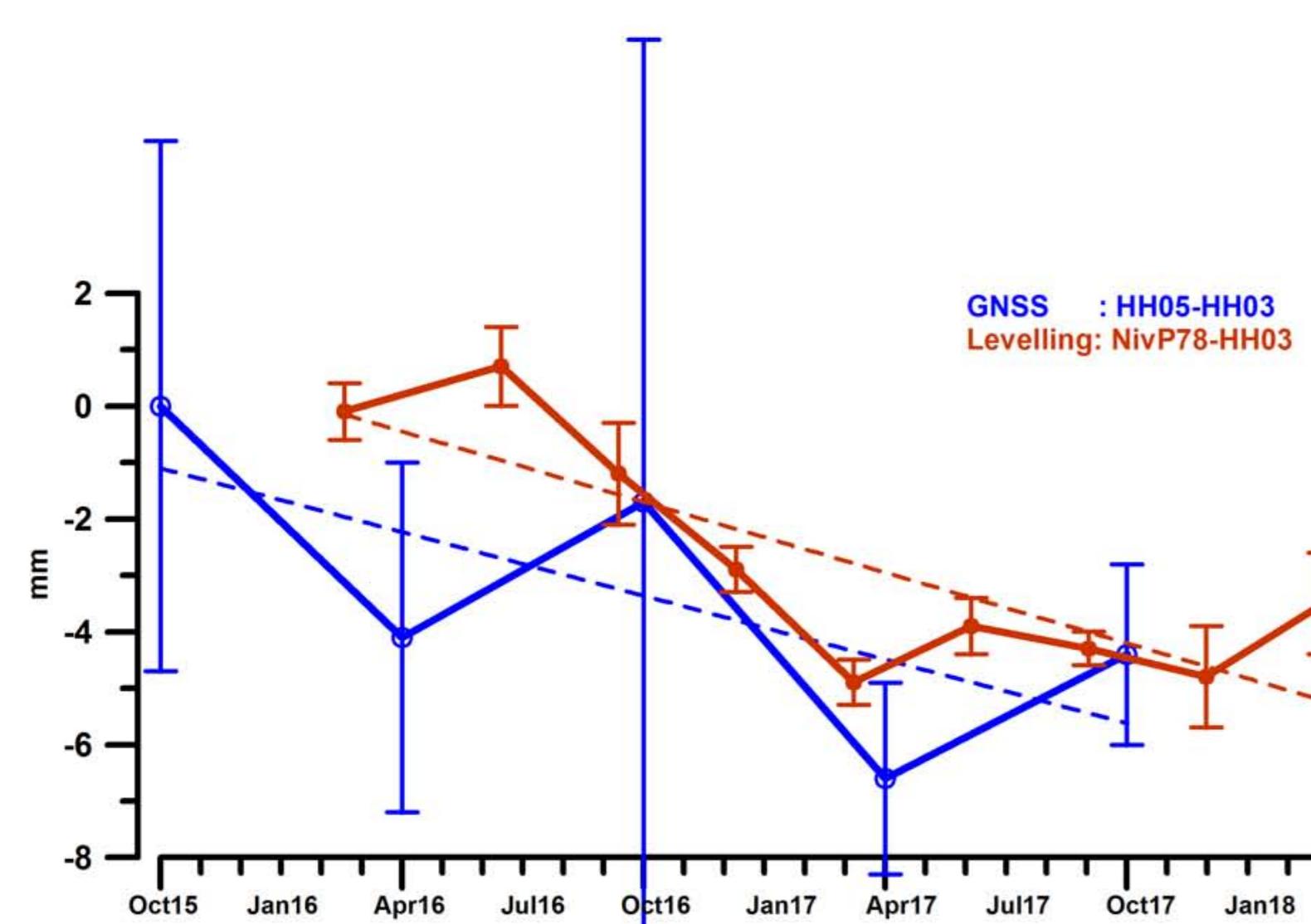


Figure 4: Temporal variation for specific height difference in the vicinity of Wobbe-See (HH03) by leveling (ref. to Niv.P78) and by GNSS (ref. to HH05). Both points are located in the north of the subsidence area.

- Subsidence processes observed although the scale of drift is very small (1.5-2 mm).
- Independent methods (levelling and GNSS) agree very well and show drift in the areas of interest.
- Results evaluated in cooperation with AP/WP 3.2 and 3.3, gravity changes between sites indicate furthermore mass transport (separation from seasonal signals), [Weise et al., 2017a, Weise et al., 2018].

Hamburg - GNSS Repeatability

Findings

- Generally, repeatability with magnitudes of 2 mm achieved, higher values caused by vegetation and frequent traffic at sites.
- Optimal location for co-location sites of interest (levelling, gravimetry) not at any time feasible, cf. Fig. 3, [Icking et al., 2016].
- Magnitudes of RMS generally at 0.3-0.4 mm and 0.2-0.3 mm (optimal sites), respectively (cf. Fig. 5).

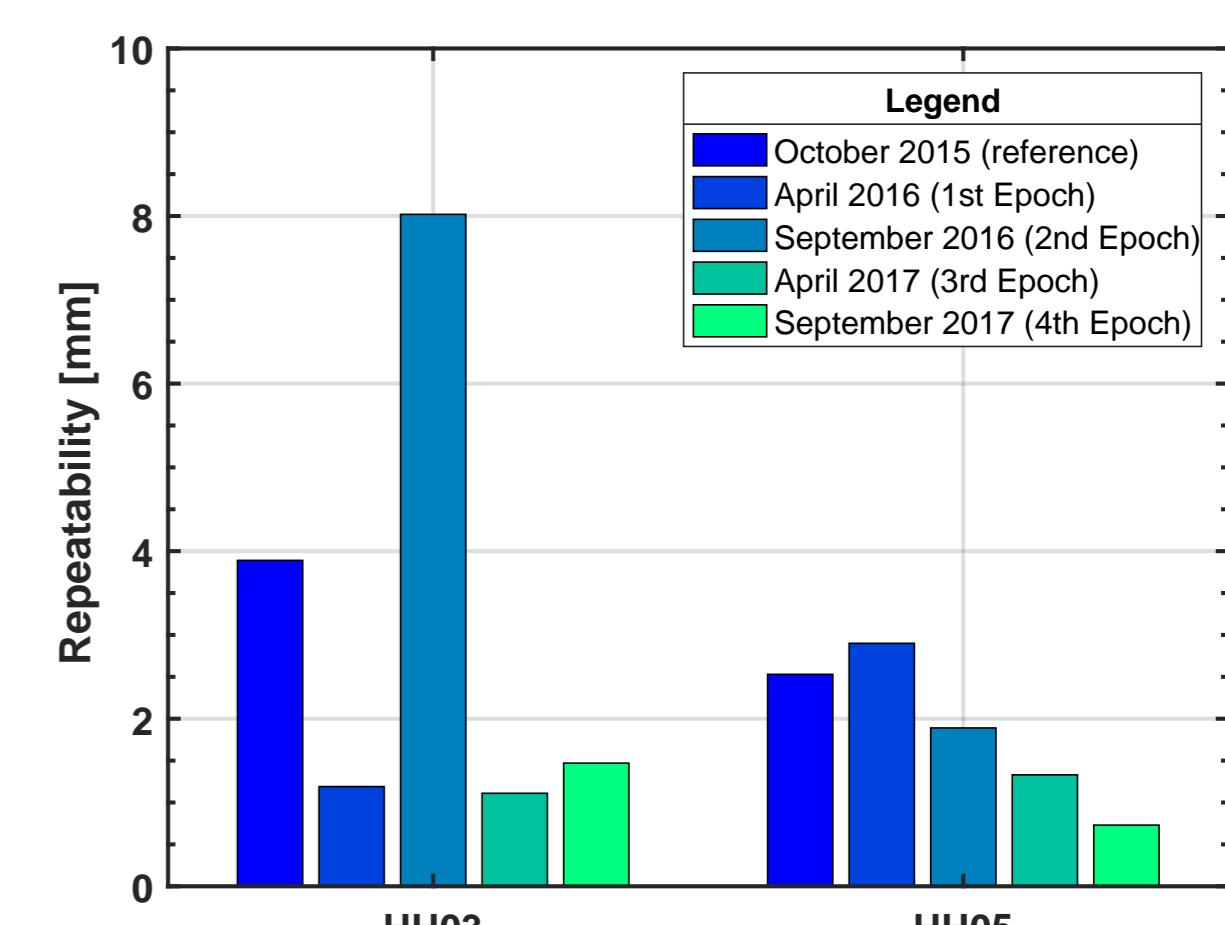
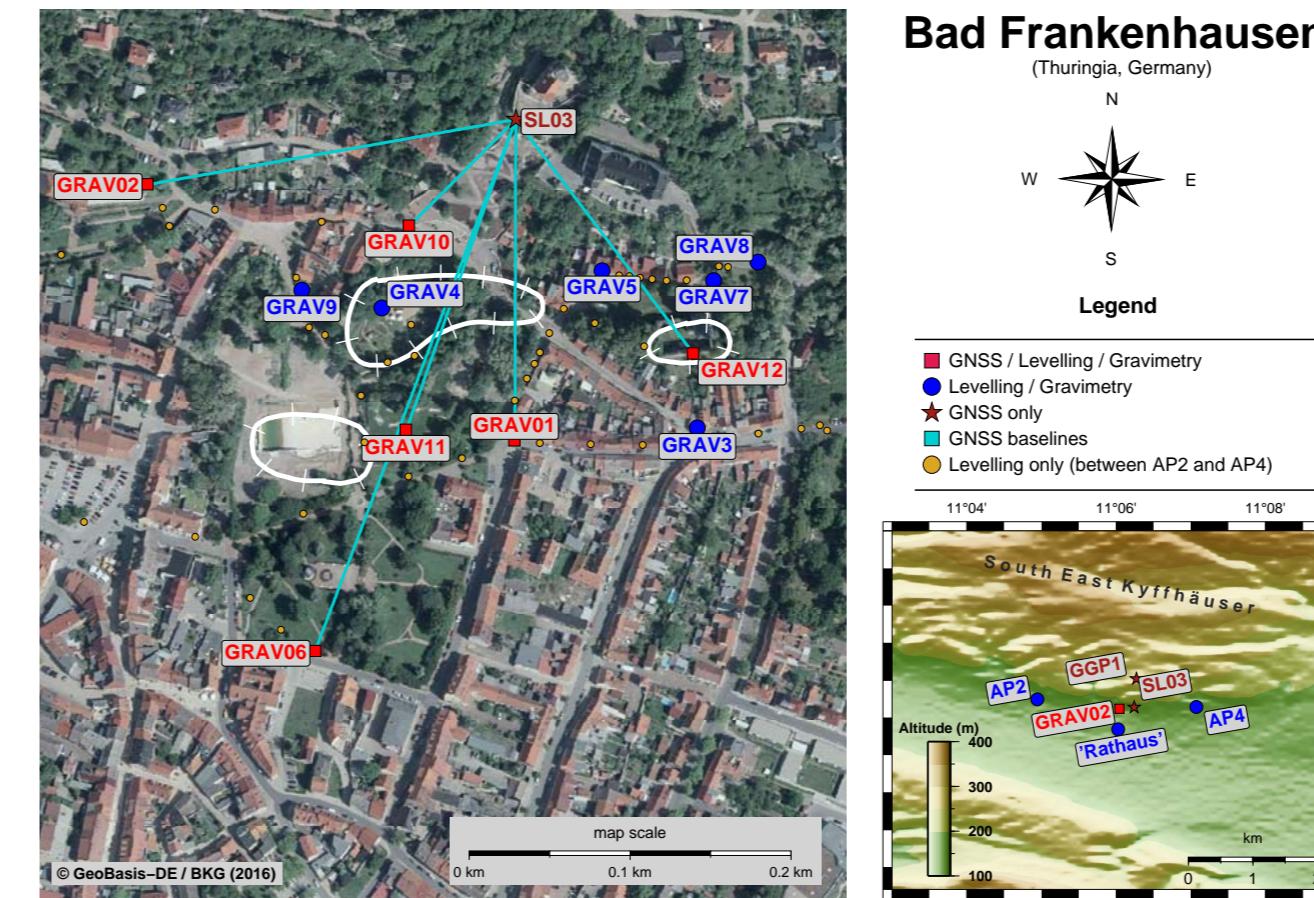
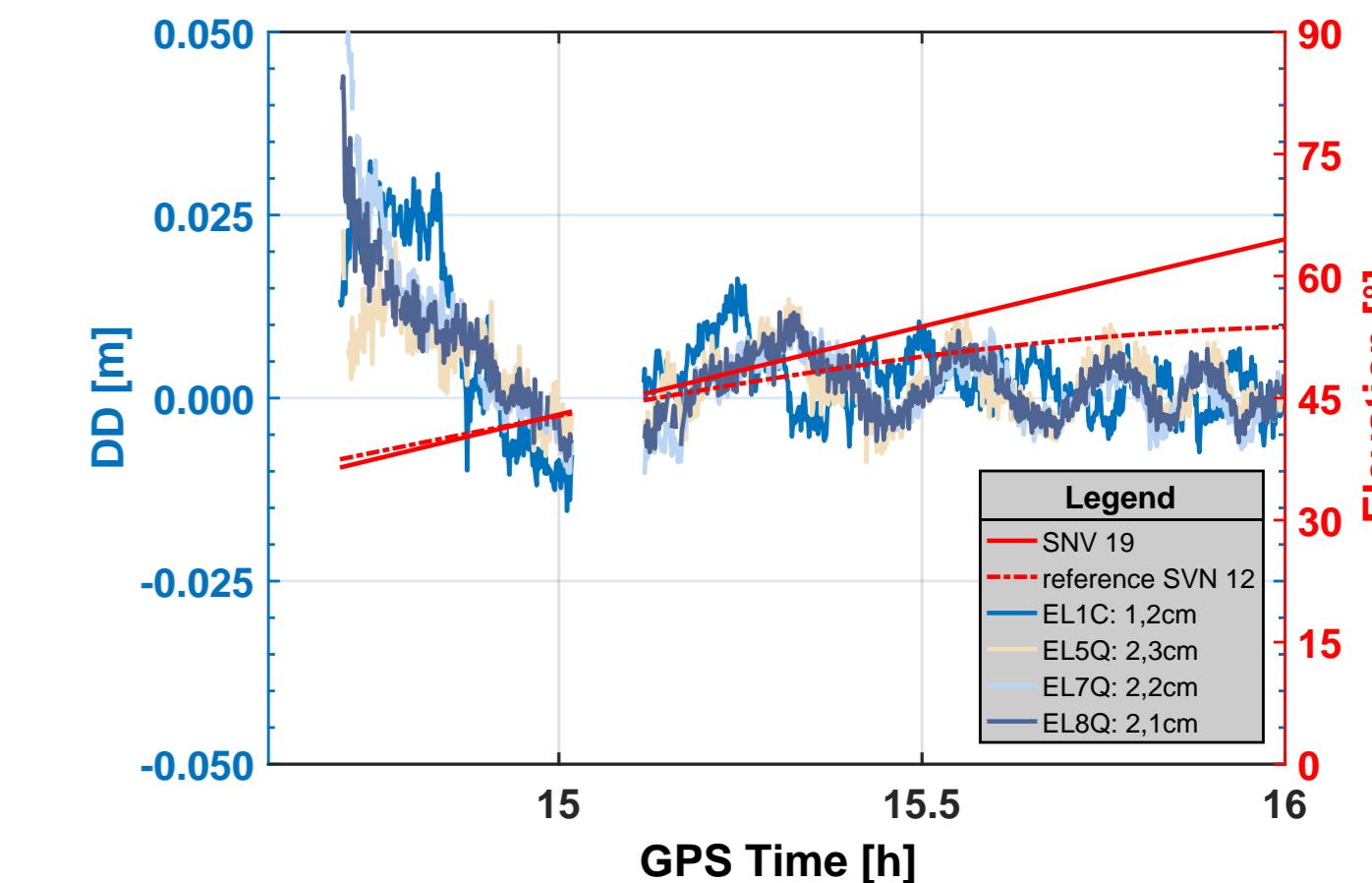


Figure 5: Characteristic repeatability of co-located sites to monitor subsidence in different scales (time, depth, spatial).

Bad Frankenhausen - Network



(a) GNSS network Bad Frankenhausen



(b) SL12: DD and elevation versus GPS Time

Figure 6: Analysis of Galileo GNSS sites, (a) network with indicated baseline, (b) double difference residuals for four hour session captured at GRAV12 (cf. Fig. 1b).

- **SL03:** Local reference station (stability check by SAPOS® stations Erfurt (0209), Buttstädt (0221), Sondershausen (0200), Mühlhausen (0214)).
- **GRAV12:** Co-located point in close vicinity to a concrete wall (located in the north of the GNSS site), challenging obstruction geometry present.
- **Baseline SL03-GRAV12 (SL-12):** 190 m, significant impact of multipath detectable.
- Multipath signatures detectable (sinusoidal) with frequencies of ≈ 20 minutes that lead to amplitudes in Galileo DDs (E5a, E5b and AltBOC E5a+b) although low noise is present. Highest noise on Galileo E1 signal detected, [Ruwisch et al., 2016].

Conclusions and Further Steps

- Study of Galileo observations in challenging, urban environments by [Ruwisch et al., 2016].
- Challenging satellite geometry improved by applying adaptive dynamic elevation masks (dynMsk) studied by [Icking et al., 2016].
- Campaigns finished and processing of epoch comparisons ongoing; solutions published frequently.
- Data provided through WebDAV server for both projects (HHX and BFH) for dedicated WP partners.

Ongoing and further steps

- Development and evaluation of integrated model for leveling and gravimetric data sets, [Kersten et al., 2017, Weise et al., 2017b].
- Quantification and separation of superimposed signals as e.g. hydrological, atmospheric, seasonal variations and tidal effects.
- Studies and application of GNSS low-cost reference stations in combination with urban infrastructure as street furniture like, e.g. streetlamps etc., [Kröger et al., 2017] to gain consistent and longer time series.

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