



On Integrated Geodetic Monitoring for Sinkhole-Induced Surface Deformation and Mass Dislocation

- JISDM2016 - Joint International Symposium on Deformation Monitoring -

Session - *Multi-Sensor-Systems for Deformation Monitoring*



SIMULTAN

Research Group

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Motivation - Research on Sinkholes / Subrosion Events



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May 30st, 2010: Sinkhole Event in Guatemala City

- ▶ tropical storm
- ▶ swallows three-storey building

Motivation - Research on Sinkholes / Subrosion Events



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February 21st, 2016: Sinkhole Event in Nordhausen

- ▶ sinkhole event in a depth of 100-150 m
- ▶ soluble rocks and subsidence of gypsum and anhydrite
- ▶ ≈ 70 000 tons of ground soil moved
- ▶ geometry: 30 m diameter and 50 m deep

SIMULTAN - A Multi-Disciplinary Joint Research Project and Group I

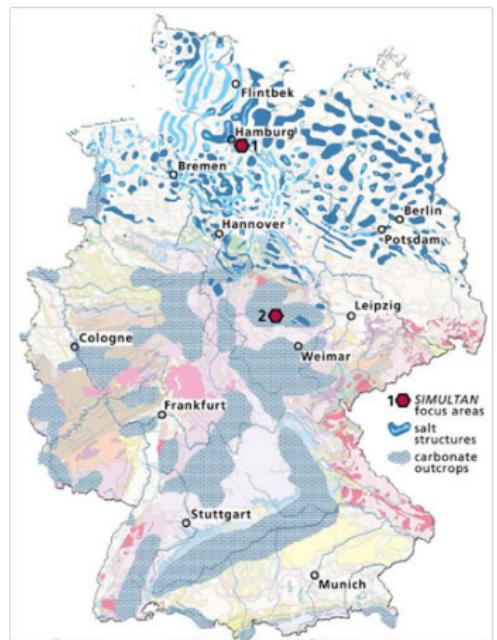
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Sinkhole Instability: Integrated **MULTi**-scale Monitoring and **ANalysis**



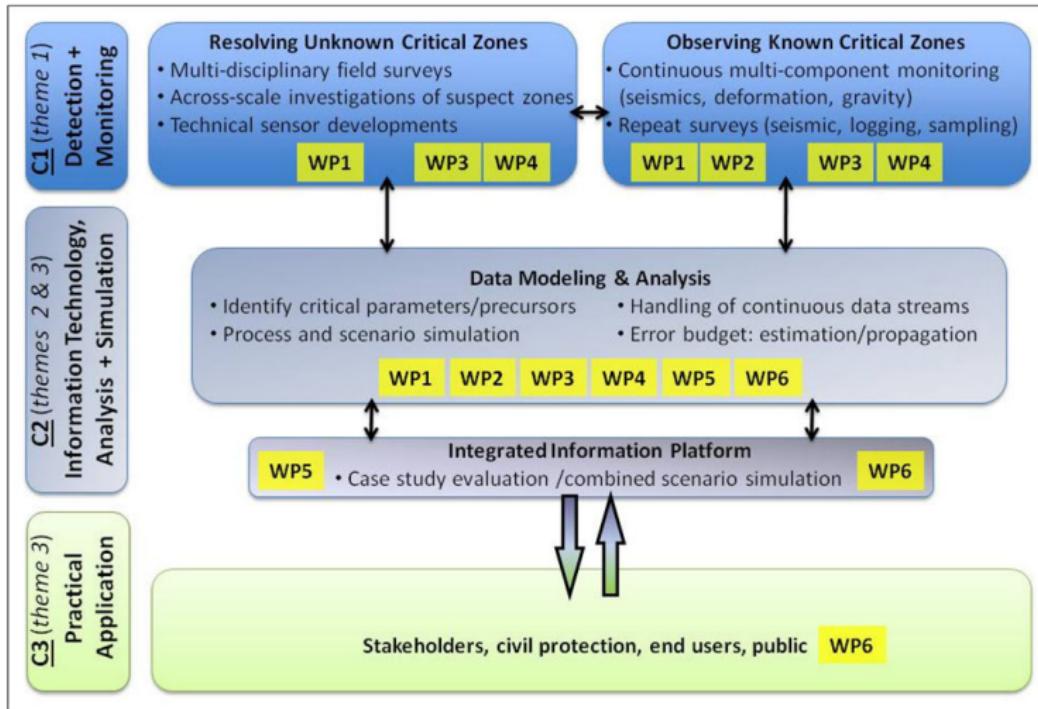
Key-Parameter

- ▶ **early recognition** concept (**different scales**: time, lateral extent and depth)
- ▶ **rigorous combination** of geodetic and geophysical techniques and data sets
- ▶ **integrated data sets** of subsurface mechanics and surface deformations by **collocated** and **co-located stations**
- ▶ **innovative** methods of urban geodetic/geophysical **monitoring strategies**



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SIMULTAN - A Multi-Disciplinary Joint Research Project and Group II



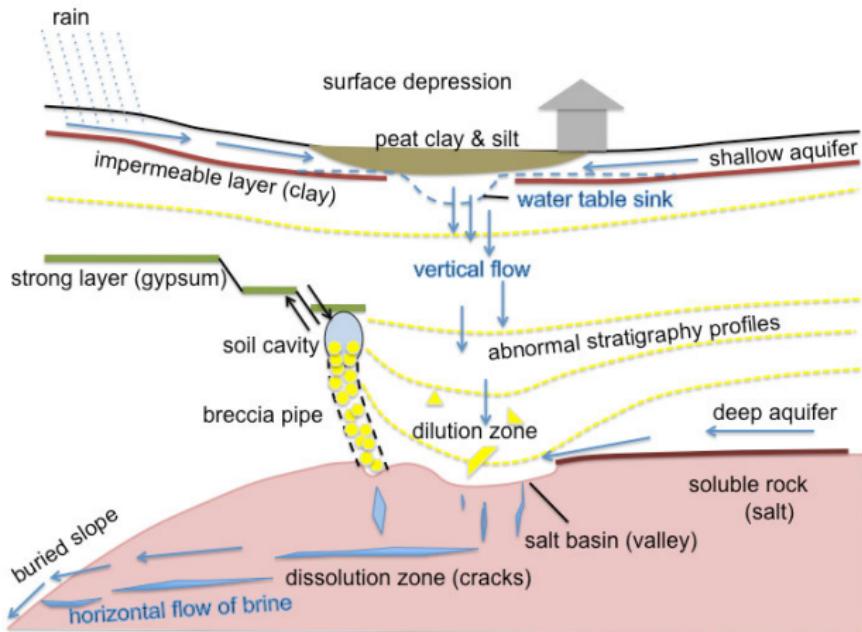
SIMULTAN - Combined Methods and Scales

Work Packages and Research Areas

- ▶ WP1: critical zones in sinkholes (LIAG)
- ▶ WP2: seismic monitoring and characterisation (UHH, GFZ, LIAG)
- ▶ WP3: surface deformation and mass dislocation (LUH, GGL, LIAG)
- ▶ WP4: rock soil water interaction in sinkhole formation (TU Berlin, UFZ)
- ▶ WP5: sub-surface cavity and collapse sinkhole evolution (GFZ, FU Berlin)
- ▶ WP6: protocols and decision process (geological surveys LLUR)

SIMULTAN - Combined Methods and Scales

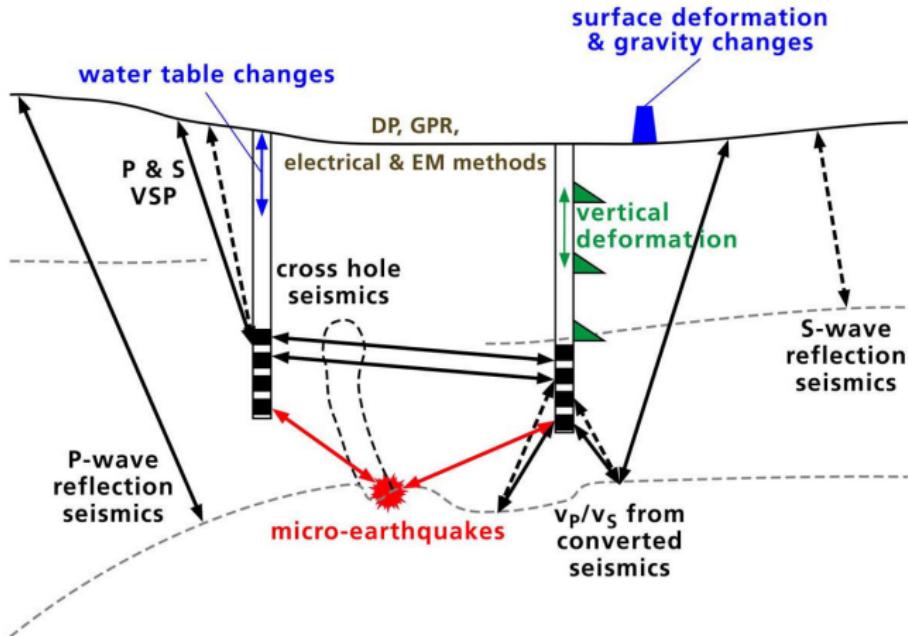
Work Packages and Research Areas



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SIMULTAN - Combined Methods and Scales

Work Packages and Research Areas



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SIMULTAN - Combined Methods and Scales

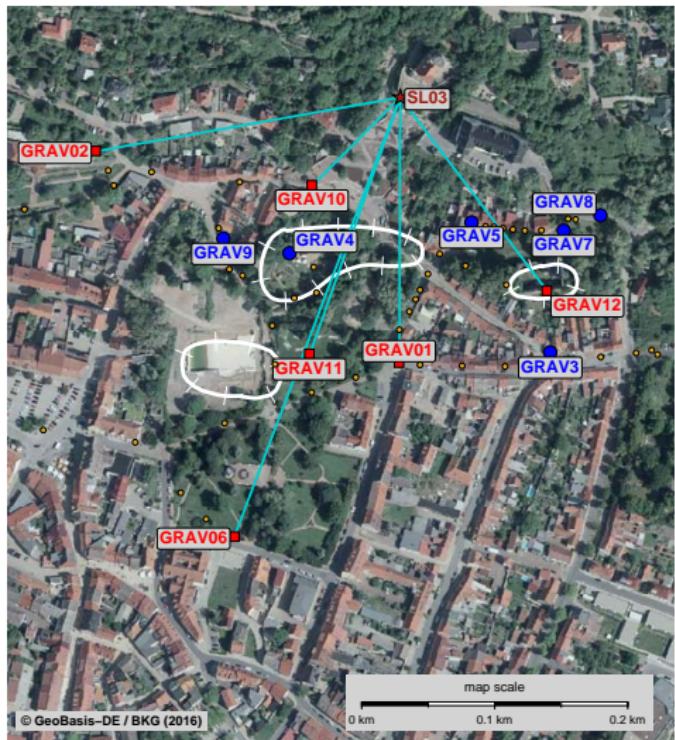
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- ▶ WP2: seismic monitoring and characterisation (UHH, GFZ, LIAG)
- ▶ **WP3: Surface Deformation and Mass Dislocation (LUH, GGL, LIAG)**
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Multi-scale Observing Techniques (geodetic & geophysical)

- ▶ Levelling (3-monthly) **LIAG**
- ▶ relative Gravimetry (3-monthly), **LIAG**
- ▶ micro-Gravimetry, **GGL**
- ▶ GNSS-Monitoring (6-monthly), **LUH**
- ▶ absolute Gravimetry (yearly), **LUH**

Multi-Technique Geo-Monitoring Network (Collocated and Co-located Sites)



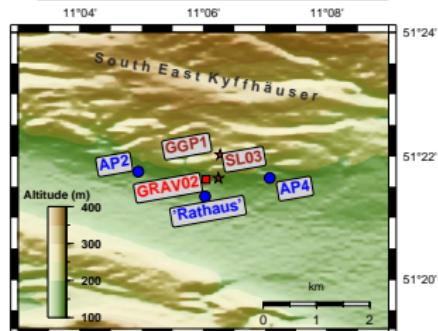
Bad Frankenhausen

(Thuringia, Germany)



Legend

- GNSS / Levelling / Gravimetry
- Levelling / Gravimetry
- ★ GNSS only
- ▬ GNSS baselines
- Levelling only (between AP2 and AP4)



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Multi-Technique Geo-Monitoring Network (Collocated and Co-located Sites)

Design of the Monitoring Network

- ▶ **120 levelling** points
- ▶ **13** (out of 120) sites for **relative gravimetry** (collocated) + 2 distal references
- ▶ **1** (of 13) site for **absolute gravimetry** (co-located by local tie to levelling mark)
- ▶ **6** (of 13) **GNSS** sites (collocated) + 2 pure GNSS points (incl. a geodetic fundamental point - GGP)



GNSS at collocated point
© LUH



absolute gravimetry
© LUH



local gravimetry tie
© LUH



relative gravimetry
© LIAG

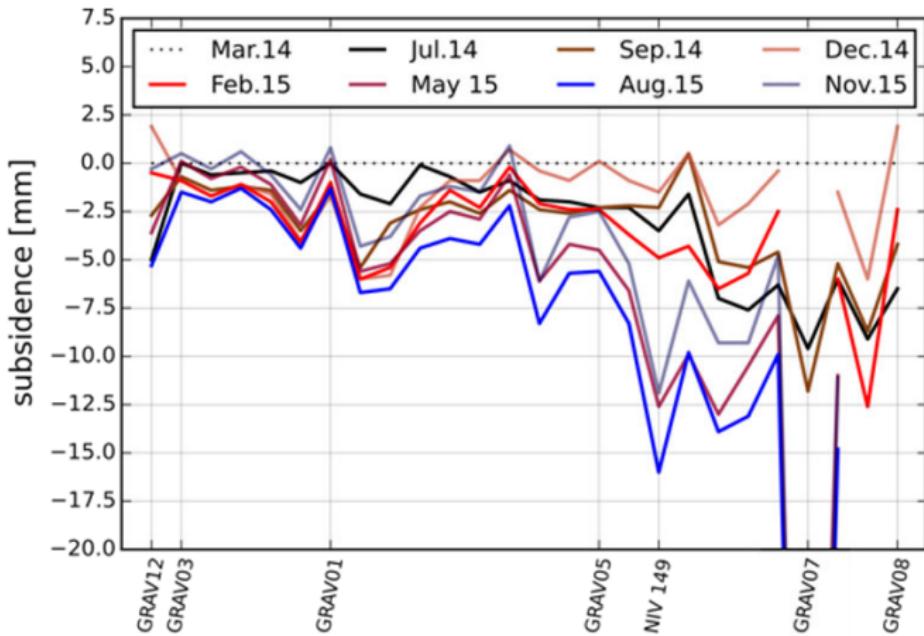


collocated point
© LIAG

Levelling Campaigns (LIAG)

Levelling Campaigns

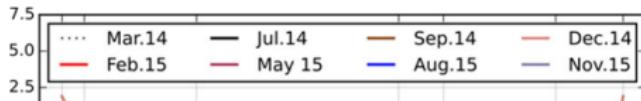
- ▶ Leica Geosystems digital level DNA03 ($\sigma_0 : \pm 0.3 \text{ mm}$) and bar code invar staffs
 - ▶ std. deviation of levelling: $\leq 1.5 \text{ mm}$
 - ▶ eight campaigns since march 2014



Levelling Campaigns (LIAG)

Levelling Campaigns

- ▶ Leica Geosystems digital level DNA03 ($\sigma_0 : \pm 0.3 \text{ mm}$) and bar code invar staffs
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Subsidence Rates - Bad Frankenhausen (Thuringia)

- ▶ verified maximum subsidence rates of 4-5 mm/yr since march 2014
- ▶ higher values for GRAV05 and GRAV08 (possibly due to extensive construction work nearby)
- ▶ time needed to separate / evaluate these effects from subrosion-induced processes



Gravimetry Campaigns - absolute and relative (LUH, LIAG)

Absolute Gravimetry

- ▶ FG5X-220 ($s \approx 0.02 \mu\text{m}/\text{s}^2$) to control gravity level (datum)
- ▶ reducing earth tides and air pressure gravity changes
- ▶ gravity tie obtained with Scintrex CG3M ($s_{\Delta g} = 0.015 \mu\text{m}/\text{s}^2$)



gravity tie measurement, © LUH

Relative Gravimetry

- ▶ gravimeter instruments used in campaigns
 - ▶ Scintrex CG3, CG5 ($s \approx 0.02 \mu\text{m}/\text{s}^2$)
 - ▶ LaCoste & Romberg ($s \approx 0.05 - 0.07 \mu\text{m}/\text{s}^2$)
- ▶ *step method* for drift control (spring gravimeters)



levelling mark to gravity tie © LUH

Gravimetry Network - Bad Frankenhausen (Thuringia)

- ▶ gravity level (datum) observed yearly by absolute gravimetry
- ▶ max. gravity difference: $44.5 \mu\text{m}/\text{s}^2$ (calibration accuracy $< 0.0445 \mu\text{m}/\text{s}^2$)
- ▶ combined adjustment of relative gravity network: $\leq 0.015 \mu\text{m}/\text{s}^2$

GNSS Campaigns - Overview (LUH)

GNSS-Equipment

- ▶ **Receiver:** Leica GRX1200+GNSS, GX1230GG and GRX1200GG Pro
- ▶ **Antennas:** Leica AR25.R3 NONE and JPS GrAnt G3T NONE (individual robot calibration @LUH)
- ▶ GNSS adaptor FG-ANA100B for precise GNSS-height determination
- ▶ atmospheric data (height differences $\geq 100\text{ m}$)



collocated point, © LUH



reference @SL03 © LUH



mock-up for calibration © LUH

Session setup

- ▶ star like network (**SL03** reliable reference station)
- ▶ 6 sessions, 4 hours observation duration
- ▶ 8 GNSS-sites, 5 employees, 3 days
- ▶ GPS only and GPS/GLONASS combined network solution (final solution: **GPS/GLO combined**)

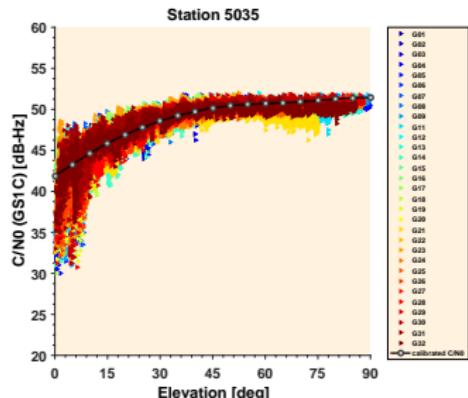
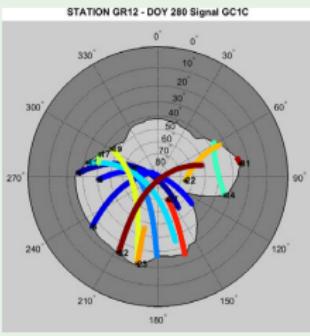
GNSS Campaign - Preparation and Challenges

Challenges for urban Monitoring Networks (GNSS)

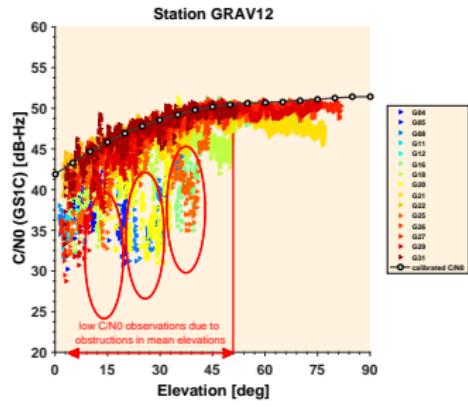
- ▶ obstruction at collocation sites due to urban reflectors
- ▶ C/N0 as quality indicator (zero baseline vs. field)
- ▶ knowledge of C/N0 reference curves (calibration)

Analysing Double Differences and C/N0s

- ▶ typical phase noise:
 $\leq \pm 3.5 \text{ mm}$ (DD on zero-baseline)
- ▶ significant variations
 $\geq \pm 3.5 \text{ mm}$ (DD in the field)
- ▶ dynamic & adaptive elevation masks
- ▶ combination of GPS and GLONASS

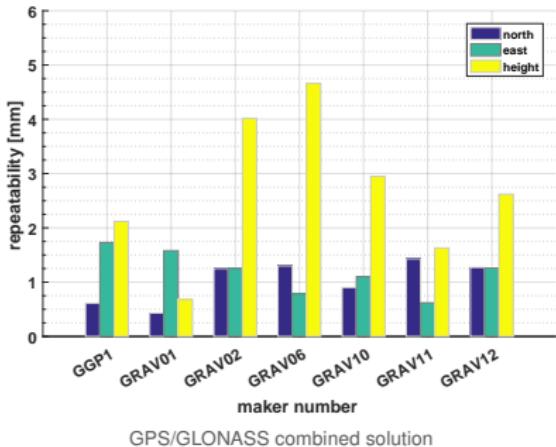
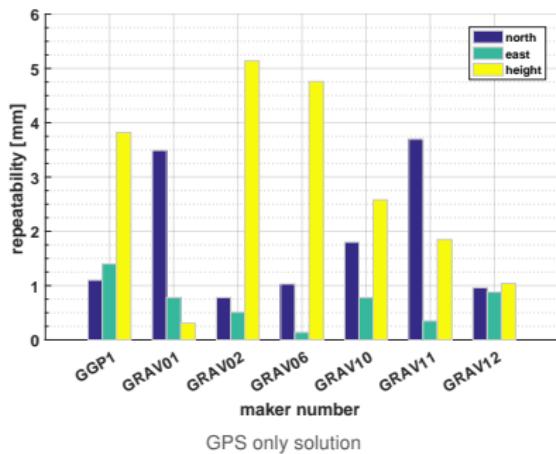


C/N0s on zero-baseline test @LUH



C/N0s in field @GRAV12

GNSS Campaign - L1-Solution of Monitoring Network



GNSS-Monitoring Network

- ▶ combined GPS/GLONASS solution optimal w.r.t. GPS only solution (L1-Solution)
- ▶ GLONASS improves observations under challenging sky distribution
- ▶ height component most challenging parameter - the effort of using FG-ANA100B and individual antenna calibrations is mandatory and justified

Comparison of GNSS and Levelling Heights

Cross-checks between GNSS-heights and Levelling

- ▶ proving GNSS-height determination using relative height differences (w.r.t. #GRAV10)
- ▶ comparing different measurement-techniques (Levelling vs. GNSS)
- ▶ validating ongoing data integration, combination and later modelling of subsurface processes

Number	Name	NHN92 Height [m]	GNSS Height [m]	ΔLevelling [m]	ΔGNSS [m]	ΔGNSS - ΔLevelling [mm]
1	GRAV01	140.2861	185.8377	-1.037	-1.039	-1.34
2	GRAV02	143.7469	189.2970	2.424	2.421	-2.81
3	GRAV06	132.7434	178.2935	-8.580	-8.583	-2.89
4	GRAV10	141.3234	186.8763	0.000	0.000	0.00
5	GRAV11	140.2651	185.8193	-1.058	-1.057	1.28
6	GRAV12	152.9325	198.4901	11.609	11.614	4.66

Cross-checks

- ▶ GNSS-heights correspond with $\pm 3\text{ mm}$ to levelling heights
- ▶ GRAV12 shows significant variation in height component (challenging visibility and geometry at this marker)

Summary and Outlook

Integrated multi-technique monitoring network

- ▶ installation and first measurements for each technique obtained
- ▶ ongoing campaigns to observe and monitor focus areas (determine deformations)
- ▶ collecting and integrating of data sets of different kind (gravimetric, GNSS, levelling, borehole extensometer, seismic)

Challenges and further work

- ▶ urban environment challenging (levelling, gravimetry, seismic, GNSS) for Hamburg/Bad Frankenhausen
- ▶ time to separate significant signals from noise (station specific evaluation)
- ▶ evaluating deformations and modelling geophysical processes and rock-soil interaction

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